## A walk in random forests

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## Random forests

Random forests are a class of algorithms used to solve regression and classification problems

- They are often used in applied fields since they handle high-dimensional settings.
- They have good predictive power and can outperform state-of-the-art methods.



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But mathematical properties of random forests remain a bit magical.

## General framework of the presentation

## Regression setting

We are given a training set $\mathcal{D}_{n}=\left\{\left(X_{1}, Y_{1}\right), \ldots,\left(X_{n}, Y_{n}\right)\right\}$ where the pairs $\left(X_{i}, Y_{i}\right) \in[0,1]^{d} \times \mathbb{R}$ are i.i.d. distributed as $(X, Y)$.

We assume that

$$
Y=m(\mathbf{X})+\varepsilon .
$$

We want to build an estimate of the regression function $m$ using random forest algorithm.

(1) Day 1: Discovering random forests

- Construction of random forests
- Infinite forest
- Centred Forests
- Median forests
(2) Day 2: Rate of consistency
- Rate of consistency for centred forests
- Rate of consistency for Median Forests
- Minimax rates for Mondrian Forests
(3) Day 3: Breiman's forests
- Consistency of Breiman forests
- Trees are built recursively by splitting the current cell into two children until some stopping criterion is satisfied.

| 400 | 380 |  | ${ }^{30}$ |
| :---: | :---: | :---: | :---: |
|  | 500 | ${ }_{0}^{100}$ | ${ }_{5}$ |
| 310 | -340 | 70 |  |
| 305 |  |  | 205 |

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k=0
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$$




Breiman Random forests are defined by
(1) A splitting rule: minimize the variance within the resulting cells.
(2) A stopping rule : stop when each cell contains less than nodesize $=2$ observations.

For a split direction $j \in\{1, \ldots, d\}$ and a split position $z \in[0,1]$, the criterion takes the form

$$
L_{n}(j, z)=\frac{1}{N_{n}(A)} \sum_{i=1}^{n}\left(Y_{i}-\bar{Y}_{A_{L}} \mathbb{1}_{\mathbf{x}_{i}^{(j)<z}}-\bar{Y}_{A_{R}} \mathbb{1}_{\mathbf{x}_{i}^{(j)} \geq z}\right)^{2},
$$

where

- $A_{L}=\left\{\mathbf{x} \in A: \mathbf{x}^{(j)}<z\right\}$ and $A_{R}=\left\{\mathbf{x} \in A: \mathbf{x}^{(j)} \geq z\right\}$
- $\bar{Y}_{A}$ is the average of the $Y_{i}$ 's belonging to $A$.
- $N_{n}(A)$ is the number of points in $A$

An example: $j=1$ and $z=0.5$.


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$$
L_{n}(1,0.5)=\frac{1}{N_{n}(A)} \sum_{i=1}^{n}(Y_{i}-\underbrace{\bar{Y}_{A_{L}} \mathbb{1}_{\mathbf{x}_{i}^{(1)}<0.5}}_{\text {Average on } A_{L}}-\bar{Y}_{A_{R}} \mathbb{1}_{\mathbf{x}_{i}^{(1)} \geq 0.5})^{2},
$$

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$$

## Construction of random forests

## Randomness in tree construction

- Resampling the data set via bootstrap;
- For each cell:
- Preselecting a subset of $m_{\text {try }}$ variables, eligible for splitting.

Random tree construction

Tree aggregation


## Construction of Breiman forests

## Breiman tree

- Select $a_{n}$ observations with replacement among the original sample $\mathcal{D}_{n}$. Use only these observations to build the tree.
- For each cell,
- Select randomly mtry coordinates among $\{1, \ldots, d\}$;
- Choose the best split along previous direction, the one minimizing the CART criterion.
- Stop when each cell contains less than nodesize observations.



## Literature

- Random forests were created by Breiman [2001].
- Many theoretical results focus on simplified version on random forests, whose construction is independent of the dataset.
[Biau et al., 2008, Biau, 2012, Genuer, 2012, Zhu et al., 2012, Arlot and Genuer, 2014]
- Analysis of more data-dependent forests:
- Asymptotic normality of random forests [Mentch and Hooker, 2015, Wager and Athey, 2017],
- Variable importance [Louppe et al., 2013],
- Rate of consistency [Wager and Walther, 2015].
- Literature review on random forests:
- Methodological review [Criminisi et al., 2011, Boulesteix et al., 2012],
- Theoretical review [Biau and Scornet, 2016]
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## A tree

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| :---: | :---: | :---: | :---: |
| 500 |  |  |  |
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- Tree estimate:

$$
m_{n}(\mathbf{x}, \Theta)=\sum_{i=1}^{n} \frac{\mathbb{1}_{\mathbf{x}_{i} \in A_{n}(\mathbf{x}, \Theta)}}{N_{n}(\mathbf{x}, \Theta)} Y_{i}
$$

where $N_{n}(\mathbf{x}, \Theta)$ is the number of points in the cell $A_{n}(\mathbf{x}, \Theta)$.


- M-Finite forest estimate :

$$
m_{M, n}\left(\mathbf{x}, \Theta_{1}, \ldots, \Theta_{M}\right)=\frac{1}{M} \sum_{m=1}^{M} m_{n}\left(\mathbf{x}, \Theta_{m}\right)
$$



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$$

Conditionally on $\mathcal{D}_{n}$, the estimate $m_{M, n}$ depends on $\Theta_{1}, \ldots, \Theta_{M}$.


- M-Finite forest estimate :

$$
m_{M, n}\left(\mathbf{x}, \Theta_{1}, \ldots, \Theta_{M}\right)=\frac{1}{M} \sum_{m=1}^{M} m_{n}\left(\mathbf{x}, \Theta_{m}\right) \underset{M \rightarrow \infty}{\mathbb{E}_{\Theta}\left[m_{n}(\mathbf{x}, \Theta)\right]}
$$

Infinite forest is better than finite forest.
(H1) One has

$$
Y=m(\mathbf{X})+\varepsilon
$$

where $\varepsilon$ is a centered Gaussian noise with finite variance $\sigma^{2}$, independent of $\mathbf{X}$.

## Theorem [Scornet, 2016]

Assume that (H2) is satisfied. Then, for all $M, n \in \mathbb{N}^{\star}$,

$$
R\left(m_{M, n}\right)=R\left(m_{\infty, n}\right)+\frac{1}{M} \mathbb{E}_{\mathbf{X}, \mathcal{D}_{n}}\left[\mathbb{V}_{\Theta}\left[m_{n}(\mathbf{X}, \Theta)\right]\right]
$$

In particular,

$$
0 \leq R\left(m_{M, n}\right)-R\left(m_{\infty, n}\right) \leq \frac{8}{M} \times\left(\|m\|_{\infty}^{2}+\sigma^{2}(1+4 \log n)\right)
$$

## A single tree versus a forest

## Theorem

We have

$$
\mathbb{E}\left[m_{M, n}\left(\mathbf{X}, \Theta_{1}, \ldots, \Theta_{M}\right)-m(\mathbf{X})\right]^{2} \leq \mathbb{E}\left[m_{n}(\mathbf{X}, \Theta)-m(\mathbf{X})\right]^{2}
$$

that is the risk of a forest is lower than the risk of each individual tree that composed the forest.

## Proof.

Jensen's inequality.

A forest is not worse than a single tree.

Different types of forests


Different types of forests


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Different types of forests

| Centred forest | Breiman's forests |
| :---: | :---: |
| Independent of $X_{i}$ and $Y_{i}$ | Dependent on $X_{i}$ and $Y_{i}$ |
|  |  |

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## A single tree



For a tree whose construction is independent of data, if
(1) $\operatorname{diam}\left(A_{n}(\mathbf{X})\right) \rightarrow 0$, in probability;
(2) $N_{n}\left(A_{n}(\mathbf{X})\right) \rightarrow \infty$, in probability;
then the tree is consistent, that is

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[m_{n}(\mathbf{X})-m(\mathbf{X})\right]^{2}=0
$$

## Consistency of purely random forests




## Theorem [Biau et al., 2008]

Consider a totally non adaptive forest of level $k$. Assume that

$$
\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right) \rightarrow 0, \quad \text { in probability } .
$$

Then, providing $k \rightarrow \infty$ and $n / 2^{k} \rightarrow \infty$, the infinite random forest is consistent, that is $R\left(m_{\infty, n}\right) \rightarrow 0$ as $n \rightarrow \infty$.
$\rightarrow$ Forest consistency results from the consistency of each tree.
$\rightarrow$ Trees are not fully developed.

## Stone Theorem

Consider an estimate of the form

$$
m_{n}(\mathbf{x})=\sum_{i=1}^{n} W_{n i}(\mathbf{x}) Y_{i}
$$

## Theorem [Stone, 1977]

Assume that the weights $W_{n i}$ are nonnegative and sum to one. Then the estimate $m_{n}$ is consistent if and only if:
(1) There is constant $C$ such that, for every measurable function $g:[0,1]^{d} \rightarrow \mathbb{R}$ with $\mathbb{E}|g(\mathbf{X})|<\infty$,

$$
\mathbb{E}\left[\sum_{i=1}^{n} W_{n i}(\mathbf{X})\left|g\left(\mathbf{X}_{i}\right)\right|\right] \leq C \mathbb{E}|g(\mathbf{X})|, \quad \text { for all } n \geq 1
$$

(2) For all $a>0, \sum_{i=1}^{n} W_{n i}(\mathbf{X}) \mathbb{1}_{\left\|\mathbf{x}_{i}-\mathbf{x}\right\|>a} \rightarrow 0$, in probability.
(0) $\max _{1 \leq i \leq n} W_{n i}(\mathbf{X}) \rightarrow 0$, in probability

## Stone theorem for a single tree

For a tree estimate

$$
m_{n}(\mathbf{x})=\sum_{i=1}^{n} Y_{i} \frac{\mathbb{1}_{\mathbf{x}_{i} \in A_{n}(\mathbf{x}, \Theta)}}{N_{n}(\mathbf{x}, \Theta)}
$$

that is

$$
W_{n i}(\mathbf{x})=\frac{\mathbb{1}_{\mathbf{x}_{i} \in A_{n}(\mathbf{x}, \Theta)}}{N_{n}(\mathbf{x}, \Theta)}
$$

1 is ok.

2 To check condition (2), note that, for all $a>0$,

$$
\begin{array}{r}
\mathbb{E}\left[\sum_{i=1}^{n} W_{n i}^{\infty}(\mathbf{X}) \mathbb{1}_{\left\|\mathbf{X}-\mathbf{X}_{i}\right\|_{\infty}>a}\right]= \\
=\mathbb{E}\left[\sum _ { i = 1 } ^ { n } \frac { \mathbb { 1 } _ { \mathbf { X } } ^ { \stackrel { \ominus } { \leftrightarrow } \mathbf { x } _ { i } } } { N _ { n } ( \mathbf { X } , \Theta ) } \mathbb { 1 } _ { \| \mathbf { X } - \mathbf { X } _ { i } \| _ { \infty } > a } \left[\sum_{i=1}^{n} \frac{\mathbb{1}_{\mathbf{X}} \stackrel{\ominus}{\leftrightarrow} \mathbf{x}_{i}}{N_{n}(\mathbf{X}, \Theta)} \mathbb{1}_{\left\|\mathbf{X}-\mathbf{X}_{i}\right\|_{\infty}>a}\right.\right. \\
\left.\times \mathbb{1}_{\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right) \geq a / 2}\right],
\end{array}
$$

because $\mathbb{1}_{\left\|\mathbf{X}-\mathbf{X}_{i}\right\|_{\infty}>a \mathbb{1}_{\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right)<a / 2}=0 \text {. Thus, }}$

$$
\begin{aligned}
& \mathbb{E}\left[\sum_{i=1}^{n} W_{n i}^{\infty}(\mathbf{X}) \mathbb{1}_{\left.\left\|\mathbf{X}-\mathbf{X}_{i}\right\|_{\infty}>a\right]} \leq \mathbb{E}\left[\mathbb{1}_{\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right) \geq a / 2}\right.\right. \\
&\left.\times \sum_{i=1}^{n} \mathbb{1}_{\mathbf{x} \oplus}^{\leftrightarrow} \mathbf{x}_{i} \mathbb{1}_{\left\|\mathbf{X}-\mathbf{X}_{i}\right\|_{\infty}>a}\right] \\
& \leq \mathbb{P}\left[\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right) \geq a / 2\right]
\end{aligned}
$$

which tends to zero, as $n \rightarrow \infty$, by assumption.

## Proof of (3)

The tree partition has $2^{k}$ cells, denoted by $A_{1}, \ldots, A_{2^{k}}$. For $1 \leq i \leq$ $2^{k}$, let $N_{i}$ be the number of points among $\mathbf{X}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n}$ falling into $A_{i}$. Finally, set $\mathcal{S}=\left\{\mathbf{X}, \mathbf{X}_{1}, \ldots, \mathbf{X}_{n}\right\}$. Since these points are independent and identically distributed, fixing the set $\mathcal{S}$ (but not the order of the points) and $\Theta$, the probability that $\mathbf{X}$ falls in the $i$-th cell is $N_{i} /(n+1)$. Thus, for every fixed $t>0$,

$$
\begin{aligned}
\mathbb{P}\left[N_{n}(\mathbf{X}, \Theta)<t\right] & =\mathbb{E}\left[\mathbb{P}\left[N_{n}(\mathbf{X}, \Theta)<t \mid \mathcal{S}, \Theta\right]\right] \\
& =\mathbb{E}\left[\sum_{i: N_{i}<t+1} \frac{N_{i}}{n+1}\right] \\
& \leq \frac{2^{k}}{n+1} t .
\end{aligned}
$$

Thus, by assumption, $N_{n}(\mathbf{X}, \Theta) \rightarrow \infty$ in probability, as $n \rightarrow \infty$.

## Proof of (3)

At last, to prove (3), note that,

$$
\begin{aligned}
\mathbb{E}\left[\max _{1 \leq i \leq n} W_{n i}^{\infty}(\mathbf{X})\right] & \leq \mathbb{E}\left[\max _{1 \leq i \leq n} \frac{\mathbb{1}_{\mathbf{x}_{i} \in A_{n}(\mathbf{X}, \Theta)}}{N_{n}(\mathbf{X}, \Theta)}\right] \\
\leq & \mathbb{E}\left[\frac{\mathbb{1}_{N_{n}(\mathbf{X}, \Theta)>0}}{N_{n}(\mathbf{X}, \Theta)}\right] \\
& \rightarrow 0 \text { as } n \rightarrow \infty,
\end{aligned}
$$

since $N_{n}(\mathbf{X}, \Theta) \rightarrow \infty$ in probability, as $n \rightarrow \infty$.
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## Construction of Median forests

Breiman tree

- Select $a_{n}$ observations with replacement among the original sample $\mathcal{D}_{n}$. Use only these observations to build the tree.
- For each cell,
- Select randomly mtry coordinates among $\{1, \ldots, d\}$;
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## Median tree

- Select $a_{n}$ observations without replacement among the original sample $\mathcal{D}_{n}$. Use only these observations to build the tree.
- For each cell,
- Select randomly mtry $=1$ coordinate among $\{1, \ldots, d\}$;
- Split at the location of the empirical median of $X_{i}$.
- Stop when each cell contains exactly nodesize $=1$ observation.


## Consistency of median forests

## Assumption (H1)

The model writes $Y=m(\mathbf{X})+\varepsilon$, where $\varepsilon$ is a centred noise such that $\mathbb{V}[\varepsilon \mid \mathbf{X}=\mathbf{x}] \leq \sigma^{2}, \mathbf{X}$ has a density on $[0,1]^{d}$ and $m$ is continuous.

## Theorem [S.(2016)]

Grant Assumption (H1). Then, provided $a_{n} \rightarrow \infty$ and $a_{n} / n \rightarrow 0$, median forests are consistent, i.e.,

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[m_{\infty, n}(\mathbf{X})-m(\mathbf{X})\right]^{2}=0
$$

## Remarks

- Good trade-off between simplicity of centred forests and complexity of Breiman's forests.
- First consistency results for fully grown trees.
- Each tree is not consistent but the forest is, because of subsampling.


## Proof of Theorem (1)

Condition ( $i$ ) in Stone's Theorem is satisfied since the regression function is uniformly continuous and $\operatorname{Var}[Y \mid \mathbf{X}=\mathbf{x}] \leq \sigma^{2}$ [see remark after Stone theorem in Györfi et al., 2002].

## Lemme 1

Assume that $\mathbf{X}$ has a density over $[0,1]^{d}$, with respect to the Lebesgue measure. Thus, the median tree satisfies, for all $\gamma$,

$$
\mathbb{P}\left[\operatorname{diam}\left(A_{n}(\mathbf{X}, \Theta)\right)>\gamma\right] \underset{n \rightarrow \infty}{\rightarrow} 0
$$

To check (3), observe that in the subsampling step, there are exactly $\binom{n-1}{a_{n}-1}$ choices to pick a fixed observation $\mathbf{X}_{i}$. Since $\mathbf{x}$ and $\mathbf{X}_{i}$ belong to the same cell only if $\mathbf{X}_{i}$ is selected in the subsampling step, we see that

$$
\mathbb{P}_{\Theta}\left[\mathbf{X} \stackrel{\Theta}{\leftrightarrow} \mathbf{X}_{i}\right] \leq \frac{\binom{n-1}{a_{n}-1}}{\binom{n}{a_{n}}}=\frac{a_{n}}{n} .
$$

So,

$$
\mathbb{E}\left[\max _{1 \leq i \leq n} W_{n i}(\mathbf{X})\right] \leq \mathbb{E}\left[\max _{1 \leq i \leq n} \mathbb{P}_{\Theta}\left[\mathbf{X} \stackrel{\ominus}{\leftrightarrow} \mathbf{X}_{i}\right]\right] \leq \frac{a_{n}}{n},
$$

which tends to zero by assumption.

## Centered forests



$$
\begin{aligned}
& k=0 \\
& k=1 \\
& k=2
\end{aligned}
$$



## Theorem (Biau [2012])

Under proper regularity hypothesis, provided $k \rightarrow \infty$ and $n / 2^{k} \rightarrow \infty$, the centred random forest is consistent.

## Consistency of centred random forest

## Estimation error [Biau, 2012]

Under proper assumptions on the regression model,

$$
\mathbb{E}\left[m_{\infty, n}^{c c}(\mathbf{X})-\bar{m}_{\infty, n}^{c c}(\mathbf{X})\right]^{2} \leq C \sigma^{2} \frac{2^{k_{n}}}{n k_{n}^{1 / 2}}
$$

Approximation error [Biau, 2012]
Under proper assumptions on the regression model,

$$
\mathbb{E}\left[\bar{m}_{\infty, n}^{c c}(\mathbf{X})-m(\mathbf{X})\right]^{2} \leq 2 d L^{2} \cdot 2^{-\frac{0.75 k_{n}}{d \log _{5} 2}}+\|m\|_{\infty}^{2} e^{-n / 2^{k_{n}}}
$$

## Consistency of centred random forest

If the forest is fully grown, that is, if $k_{n}=\left\lfloor\log _{2} n\right\rfloor$

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$$

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- Select randomly mtry $=1$ coordinate among $\{1, \ldots, d\}$;
- Split at the location of the empirical median of $X_{i}$.
- Stop when each cell has been cut $k$ times (i.e., nodesize $\simeq\left\lfloor a_{n} / 2^{k}\right\rfloor$ ).


## Rate of consistency

## Assumption (H1)

The regression model writes $Y=m(\mathbf{X})+\varepsilon$, where $\mathbf{X}$ is uniformly distributed on $[0,1]^{d}, m$ is L-Lipschitz, and $\varepsilon \sim \mathcal{N}\left(0, \sigma^{2}\right)$.

## Theorem [Duroux, S.(2018)]

Grant (H1). For all $n$, for all $\mathbf{x} \in[0,1]^{d}$, if $a_{n} \geq 2^{k}$, then

$$
\mathbb{E}\left[m_{\infty, n}(\mathbf{x})-m(\mathbf{x})\right]^{2} \leq 2 \sigma^{2} \frac{2^{k}}{n}+d L^{2} C_{1}\left(1-\frac{3}{4 d}\right)^{k}
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- Right-hand side: Estimation error + approximation error.


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- Consistency result for each tree if $2^{k} / a_{n} \rightarrow 0$ and $k \rightarrow \infty$.


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- Right-hand side: Estimation error + approximation error.
- Consistency result for each tree if $2^{k} / a_{n} \rightarrow 0$ and $k \rightarrow \infty$.
- The upper bound is independent of $a_{n}$.


## Rate of consistency

Let $\beta=1-3 /(4 d)$ and $k_{n}^{\star}=\left(\ln (n)+C_{2}\right) /(\ln 2-\ln \beta)$.

## Theorem [Duroux, S.(2018)]

Assume that (H1) is satisfied. Consider a median forest of level $k=k_{n}^{\star}$. For all $n$, for all $\mathbf{x} \in[0,1]^{d}$, if $a_{n} \geq 2^{k_{n}^{*}}$,

$$
\mathbb{E}\left[m_{\infty, n}(\mathbf{x})-m(\mathbf{x})\right]^{2} \leq C n^{\frac{\ln \beta}{\ln ^{2-\ln \beta}}} .
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The previous theorem holds in particular for two regimes:

- $a_{n}=n$ : the median forest is not fully grown $\left(2^{k_{n}^{*}} / n \rightarrow 0\right)$ and the whole data set is used to build each tree.
- $a_{n}=2^{k_{n}^{\star}}$ : the median forest is fully grown and the subsampling rate $a_{n} / n \rightarrow 0$.


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No need for tuning them both at the same time.

- Construction of random forests
- Infinite forest
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- Median forests
(2) Day 2: Rate of consistency
- Rate of consistency for centred forests
- Rate of consistency for Median Forests
- Minimax rates for Mondrian Forests
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- $\operatorname{MP}(\lambda, C)$ : distribution on recursive, axis-aligned partitions of $C=\prod_{j=1}^{d}\left[a_{j}, b_{j}\right] \subset \mathbb{R}^{d}(=$ trees $)$.
- $\lambda>0$ "lifetime" $=$ complexity parameter.

- Start with cell $C$ (root), formed at time $\tau_{C}=0$.
- Sample time till split $E \sim \operatorname{Exp}(|C|)$ with $|C|:=\sum_{j=1}^{d}\left(b_{j}-a_{j}\right)$
- If $\tau_{C}+E \leq \lambda$,
- split $C$ in $C_{L}=\left\{x \in C: x_{J} \leq S_{J}\right\}$ and $C_{R}=C \backslash C_{L}$ :
- split coordinate $J \in\{1, \ldots, d\}$ with $\mathbb{P}(J=j)=\frac{b_{j}-a_{j}}{|A|}$,
- split threshold $S_{J} \mid J \sim \mathcal{U}\left(\left[a_{J}, b_{J}\right]\right)$
- Apply the procedure to $\left(C_{L}, \tau_{C}+E\right),\left(C_{R}, \tau_{C}+E\right)$.
- Else don't split $C$ (which becomes a leaf of the tree).

- Introduced in [ ${ }^{1}$ ] for computational reasons: predictions updated efficiently with new sample point (online algorithm).
- Approximately: sample independent partitions $\Pi_{\lambda}^{(1)}, \ldots, \Pi_{\lambda}^{(M)} \sim \operatorname{MP}\left(\lambda,[0,1]^{d}\right)$, fit them and average their predictions.
- No theoretical analysis of the algorithm.
- Choice of the parameter $\lambda$ ?
${ }^{1}$ Lakshminarayanan, Roy, Teh. Mondrian forests: Efficient online random forests. In NIPS, 2014.

Denote $m_{\lambda, M, n}$ the (randomized) Mondrian forest estimator with $M$ trees and parameter $\lambda$ Let

$$
\text { (H) } \operatorname{Var}(Y \mid X) \leq \sigma^{2}<\infty \text { a.s. }
$$

## Theorem (Mourtada, Gaïffas, S.)

Assume ( $\mathbf{H}$ ) and that the regression function $m$ is L-Lipschitz. Then:

$$
\begin{equation*}
\mathcal{R}\left(m_{\lambda, M, n}\right) \leq \frac{4 d L^{2}}{\lambda^{2}}+\frac{(1+\lambda)^{d}}{n}\left(2 \sigma^{2}+9\|m\|_{\infty}^{2}\right) \tag{1}
\end{equation*}
$$

In particular, the choice $\lambda:=\lambda_{n} \asymp n^{1 /(d+2)}$ gives

$$
\begin{equation*}
\mathcal{R}\left(m_{\lambda, M, n}\right)=O\left(n^{-2 /(d+2)}\right), \tag{2}
\end{equation*}
$$

which is the minimax optimal rate for the estimation of a Lipschitz function in dimension $d$.

- The above result is true for every $M \geq 1$ (number of trees): in particular, a single tree is already optimal for the estimation of a Lipschitz function in dimension $d$.
- In practice, forests with $M \gg 1$ perform better than trees.
- How to account for this ? Do we gain something by randomizing partitions?
- When is $M$ "large enough" ?


## Improved rates under $\mathscr{C}^{2}$ regularity

## Theorem (Mourtada, Gaiiffas, S.)

Assume (H), $\underline{m}$ of class $\mathscr{C}^{2}$, and that $\mathbf{X}$ has a positive, Lipschitz density on $[0,1]^{d}$. Then, for every $\varepsilon>0$ :

$$
\mathcal{R}_{[\varepsilon, 1-\varepsilon]^{d}}\left(m_{\lambda, M, n}\right)=O\left(\frac{1}{M \lambda^{2}}+\frac{1}{\lambda^{4}}+\frac{e^{-\lambda \varepsilon}}{\lambda^{3}}+\frac{(1+\lambda)^{d}}{n}\right)
$$

For $\lambda:=\lambda_{n} \asymp n^{1 /(d+4)}$ and $M:=M_{n} \gtrsim n^{2 /(d+4)}$, this implies

$$
\mathcal{R}_{[\varepsilon, 1-\varepsilon]^{d}}\left(m_{\lambda, M, n}\right)=O\left(n^{-4 /(d+4)}\right)
$$

which is the optimal rate for twice differentiable $m$ in dimension $d$. Without conditioning, we get $O\left(n^{-3 /(d+3)}\right)$ (boundary effect). By contrast, Mondrian trees do not exhibit improved rates.

Remark: Similar result obtained by Arlot and Genuer (2014) in dimension 1 for another variant of Random forests.

- Bias-variance decomposition: standard decomposition in approximation error + estimation error.
- Exact geometric properties (local and global) of Mondrian partitions are directly available, without reasoning conditionally on the graph structure / on earlier splits.
- Restriction property: enables to obtain the exact distribution of the cell $C_{\lambda}(x)$ of $x \in[0,1]^{d}$ in the partition $\Pi_{\lambda} \sim \operatorname{MP}\left(\lambda,[0,1]^{d}\right)$ (4 lines proof).
- By modifying the distribution of the Mondrian and using the one-dimensional case, one can show that the expected number of leaves in $\Pi_{\lambda}$ is $(1+\lambda)^{d}$.


## Online implementation and adaptivity to smoothness

- If $m: x \mapsto \mathbb{E}[Y \mid X=x]$ is $\alpha$-Hölder $(\alpha \in(0,1])$, optimal rate $\mathcal{R}\left(\widehat{f}_{\lambda, n}\right)=O\left(n^{-2 \alpha /(d+2 \alpha)}\right)$ for $\lambda \asymp n^{-1 /(d+2 \alpha)}$.
- In practice, $\alpha$ is unknown. How to choose $\lambda$ ?
- Exponentially weighted aggregation over the class of all finite labeled subtrees of the "infinite Mondrian" $\Pi_{\infty}$. BUT: infinite tree (sampled from the start ??) + number of subtrees exponential in the number of nodes.
- Extension properties of Mondrian + efficient algorithm for branching process prior ("Context Tree Weighting": one weight per node) $\Longrightarrow$ online and efficient exact algorithm $(O(\log n)$ update, $O(n \log n)$ training time, $O(\log n)$ prediction).
- Resulting $\widehat{m}_{n}$ is adaptive to $\alpha$ : $\mathcal{R}\left(\widehat{m}_{n}\right)=\widetilde{O}\left(n^{-2 \alpha /(d+2 \alpha)}\right)$.
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## Construction of Breiman forests

Breiman tree

- Select $a_{n}$ observations with replacement among the original sample $\mathcal{D}_{n}$. Use only these observations to build the tree.
- For each cell,
- Select randomly mtry coordinates among $\{1, \ldots, d\}$;
- Choose the best split along previous direction, the one minimizing the CART criterion.
- Stop when each cell contains less than nodesize observations.


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## Our Breiman tree

- Select $a_{n}$ observations without replacement among the original sample $\mathcal{D}_{n}$. Use only these observations to build the tree.
- For each cell,
- Select randomly mtry coordinates among $\{1, \ldots, d\}$;
- Choose the best split along previous direction, the one minimizing the CART criterion.
- Stop when the number of cells is exactly $t_{n}$.


## Additive regression model

## Assumption (H1)

The regression model is

$$
Y=\sum_{j=1}^{d} m_{j}\left(\mathbf{X}^{(j)}\right)+\varepsilon,
$$

where $\varepsilon \sim \mathcal{N}\left(0, \sigma^{2}\right)$ with $\varepsilon$ independent of $\mathbf{X} ; \mathbf{X}$ is uniformly distributed on $[0,1]^{d}$; each model component $m_{j}$ is continuous.

## Consistency

## Assumption (H1)

The regression model is $Y=\sum_{j=1}^{d} m_{j}\left(\mathbf{X}^{(j)}\right)+\varepsilon$, where $\varepsilon \sim \mathcal{N}\left(0, \sigma^{2}\right)$ with $\varepsilon$ independent of $\mathbf{X} ; \mathbf{X}$ is uniformly distributed on $[0,1]^{d}$; each model component $m_{j}$ is continuous.

## Theorem [Scornet et al., 2015]

Assume that (H1) is satisfied. Then, provided $a_{n} \rightarrow \infty$ and $t_{n}\left(\log a_{n}\right)^{9} / a_{n} \rightarrow 0$, random forests are consistent, i.e.,

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[m_{\infty, n}(\mathbf{X})-m(\mathbf{X})\right]^{2}=0
$$

## Remarks

- First consistency result for Breiman's original forest.
- Consistency of CART.

$$
\Delta(m, A)=\sup _{\mathbf{x}, \mathbf{x}^{\prime} \in A}\left|m(\mathbf{x})-m\left(\mathbf{x}^{\prime}\right)\right| .
$$

Furthermore, we denote by $A_{n}(\mathbf{X}, \Theta)$ the cell of a tree built with random parameter $\Theta$ that contains the point $\mathbf{X}$.

## Proposition

Assume that (H1) holds. Then, for all $\rho, \xi>0$, there exists $N \in \mathbb{N}^{\star}$ such that, for all $n>N$,

$$
\mathbb{P}\left[\Delta\left(m, A_{n}(\mathbf{X}, \Theta)\right) \leq \xi\right] \geq 1-\rho
$$

Theoretical splitting criterion for a split $(j, z)$ :

$$
\begin{aligned}
L^{\star}(j, z)=\mathbb{V} & {[Y \mid \mathbf{X} \in A]-\mathbb{P}\left[\mathbf{X}^{(j)}<z \mid \mathbf{X} \in A\right] \mathbb{V}\left[Y \mid \mathbf{X}^{(j)}<z, \mathbf{X} \in A\right] } \\
& -\mathbb{P}\left[\mathbf{X}^{(j)} \geq z \mid \mathbf{X} \in A\right] \mathbb{V}\left[Y \mid \mathbf{X}^{(j)} \geq z, \mathbf{X} \in A\right] .
\end{aligned}
$$

- Assume that (H1) is satisfied. Then, for all $\mathbf{x} \in[0,1]^{p}$,

$$
\Delta\left(m, A_{k}^{\star}(\mathbf{x}, \Theta)\right) \rightarrow 0, \quad \text { almost surely, as } k \rightarrow \infty .
$$

- Assume that (H1) is satisfied. Fix $\mathbf{x} \in[0,1]^{p}, k \in \mathbb{N}^{\star}$, and let $\xi>0$. Then $L_{n, k}(\mathbf{x}, \cdot)$ is stochastically equicontinuous on $\overline{\mathcal{A}}_{k}^{\xi}(\mathbf{x})$, that is, for all $\alpha, \rho>0$, there exists $\delta>0$ such that

$$
\lim _{n \rightarrow \infty} \mathbb{P}\left[\sup _{\substack{\left\|\mathbf{d}_{k}-\mathbf{d}_{k}^{\prime}\right\|_{\infty} \leq \delta \\ \mathbf{d}_{k}, \mathbf{d}_{k}^{\prime} \in \overline{\mathcal{A}}_{k}^{\xi}(\mathbf{x})}}\left|L_{n, k}\left(\mathbf{x}, \mathbf{d}_{k}\right)-L_{n, k}\left(\mathbf{x}, \mathbf{d}_{k}^{\prime}\right)\right|>\alpha\right] \leq \rho
$$

- Assume that (H1) is satisfied. Fix $\xi, \rho>0$ and $k \in \mathbb{N}^{\star}$. Then there exists $N \in \mathbb{N}^{\star}$ such that, for all $n \geq N$,

$$
\mathbb{P}\left[d_{\infty}\left(\hat{\mathbf{d}}_{k, n}(\mathbf{X}, \Theta), \mathcal{A}_{k}^{\star}(\mathbf{X}, \Theta)\right) \leq \xi\right] \geq 1-\rho
$$

We let $\mathcal{F}_{n}(\Theta)$ be the set of all functions $f:[0,1]^{d} \rightarrow \mathbb{R}$ piecewise constant on each cell of the partition $\mathcal{P}_{n}(\Theta)$

## Theorem [Györfi et al., 2002]

Let $m_{n}$ and $\mathcal{F}_{n}(\Theta)$ be as above. Assume that
(i) $\lim _{n \rightarrow \infty} \beta_{n}=\infty$,
(ii) $\lim _{n \rightarrow \infty} \mathbb{E}\left[\inf _{\substack{f \in \mathcal{F}_{n}(\Theta) \\\|f\|_{\infty} \leq \beta_{n}}} \mathbb{E}_{\mathbf{X}}[f(\mathbf{X})-m(\mathbf{X})]^{2}\right]=0$,
(iii) For all $L>0$,

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[\sup _{\substack{f \in \mathcal{F}_{n}(\Theta) \\\|f\|_{\infty} \leq \beta_{n}}} \left\lvert\, \frac{1}{a_{n}} \sum_{i \in \mathcal{I}_{n, \Theta}}\left[f\left(\mathbf{X}_{i}\right)-Y_{i, L}\right]^{2}-\mathbb{E}\left[f(\mathbf{X})-Y_{L}\right]^{2}\right. \|\right]=0 .
$$

Then

$$
\lim _{n \rightarrow \infty} \mathbb{E}\left[T_{\beta_{n}} m_{n}(\mathbf{X}, \Theta)-m(\mathbf{X})\right]^{2}=0
$$

According to the Proposition

## Proposition

Assume that (H1) holds. Then, for all $\rho, \xi>0$, there exists $N \in \mathbb{N}^{\star}$ such that, for all $n>N$,

$$
\mathbb{P}\left[\Delta\left(m, A_{n}(\mathbf{X}, \Theta)\right) \leq \xi\right] \geq 1-\rho
$$

the statement (ii) holds.
The second one is true because the complexity of the partition is controlled by the condition $t_{n}\left(\log a_{n}\right)^{9} / a_{n} \rightarrow 0$.

## Sparsity and Breiman's forests

## Assumption

Assume that,

$$
Y=\sum_{\ell=1}^{S} m_{\ell}\left(\mathbf{X}^{(\ell)}\right)+\varepsilon
$$

for some $S<d$ and that, for each cell, the best split is selected among all $d$ variables

## Proposition [Scornet et al., 2015]

Let $k \in \mathbb{N}^{\star}$ and $\xi>0$. Under appropriate assumptions, with probability $1-\xi$, for all $n$ large enough, we have, for all $1 \leq q \leq k$,

$$
j_{q, n}(\mathbf{X}) \in\{1, \ldots, S\},
$$

where $j_{1, n}(\mathbf{X}), \ldots, j_{k, n}(\mathbf{X})$ are the first $k$ splitting directions used to construct the cell containing $\mathbf{X}$

## Conclusion

- Centred forests: Trees and forests are consistent.
- Median forests
- A single tree is not consistent but the forest is.
$\rightarrow$ Benefits from using a random forest compared to a single tree.
- Asymptotic to optimize subsampling size and tree depth.
$\rightarrow$ No need to tune them both at the same time.
- Mondrian forests
- Achieve minimax rate for both $\mathscr{C}^{1}$ and $\mathscr{C}^{2}$ functions $\rightarrow$ For $\mathscr{C}^{2}$ functions, a tree is not optimal but the forest is.
- Breiman forests
- Trees and forests are consistent and relevant feature selection $\rightarrow$ Good performance in high-dimensional settings.



## Thank you!

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